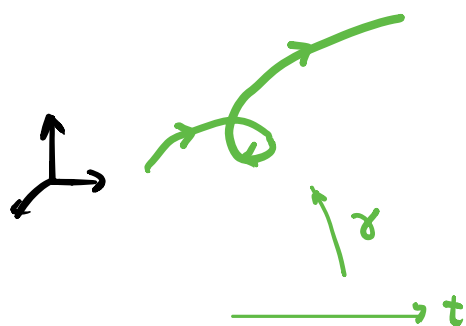


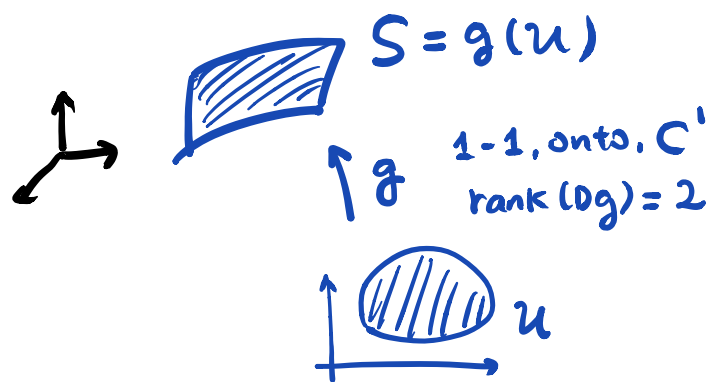
MATH 2028 Integration on submanifolds of \mathbb{R}^n

Goal: Define k -dimensional submanifolds of \mathbb{R}^n and discuss how to do integration on them.

Recall: Curves in \mathbb{R}^n



Surfaces in \mathbb{R}^3



We first generalize it to any dimension.

Defⁿ: A k -dimensional parametrized submanifold of \mathbb{R}^n is a C^1 map $g: U \xrightarrow{\text{open}} \mathbb{R}^k \rightarrow \mathbb{R}^n$ s.t.

- g is 1-1, onto its image $S = g(U)$
- $\text{rank}(Dg) = k$ everywhere in U

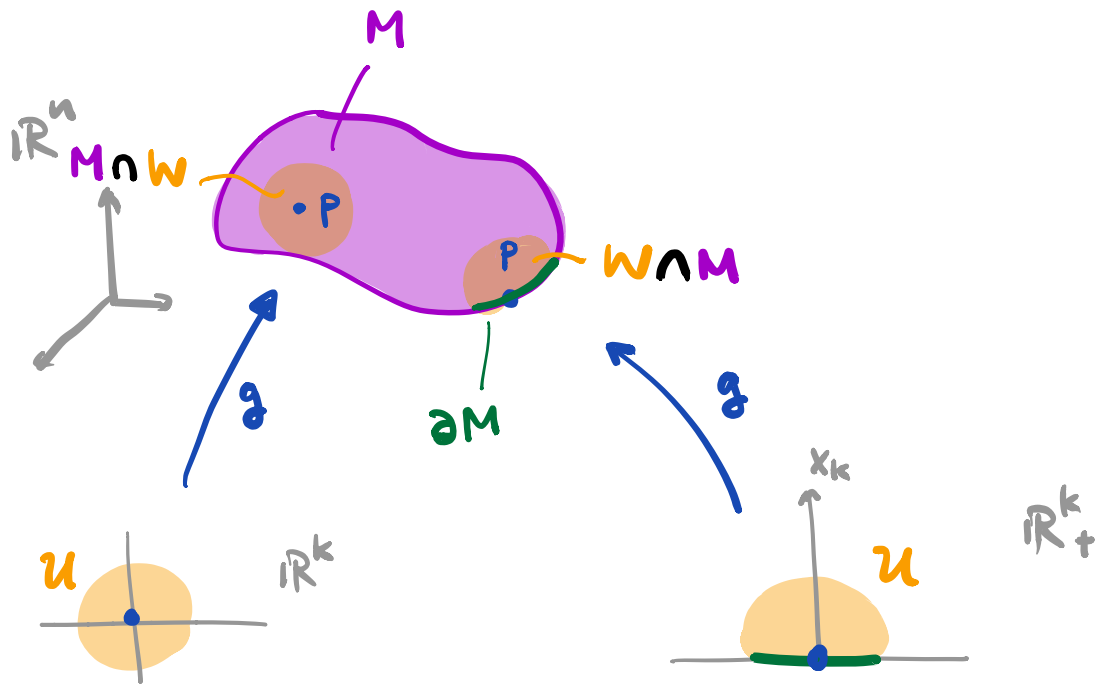
Any such g is called a parametrization of S .

We can piece together such parametrized submanifolds to form a global submanifold, which may not be expressed globally by a single parametrization (e.g. spheres).

Defⁿ: A subset $M \subseteq \mathbb{R}^n$ is called a k -dimensional submanifold of \mathbb{R}^n with boundary if $\forall p \in M$, $\exists W \subseteq \mathbb{R}^n$ ^{open} containing p and a parametrization $g: U \rightarrow \mathbb{R}^n$ s.t.

(i) $g(U) = W \cap M$

(ii) $U \subseteq \mathbb{R}^k$ ^{open} or $U \subseteq \mathbb{R}_+^k := \{x_k \geq 0\}$



Note that the **tangent space** $T_p M$ at $p \in M$ is spanned by the basis (denote $g = g(u_1, \dots, u_k)$)

$$\left\{ \frac{\partial g}{\partial u_1}, \frac{\partial g}{\partial u_2}, \dots, \frac{\partial g}{\partial u_k} \right\} \subseteq T_p M$$

Using this basis, we can define

$$g_{ij} := \frac{\partial g}{\partial u_i} \cdot \frac{\partial g}{\partial u_j} \quad i, j = 1, \dots, k$$

Denote (g_{ij}) to be the $k \times k$ matrix.

Defⁿ: For any cts function $f: M \rightarrow \mathbb{R}$ on a k -dimensional submanifold $M \subseteq \mathbb{R}^n$ parametrized by $g: U \rightarrow M = g(U)$, we define the integral of f as

$$\int_M f \, d\sigma := \int_U f \circ g \cdot \sqrt{\det(g_{ij})} \, dV$$

In particular, $\text{Area}(M) := \int_M 1 \, d\sigma$.

Example: Let $M \subseteq \mathbb{R}^4$ be the 2-dim'l submanifold parametrized by $g: (0, 2\pi) \times (0, 2\pi) \rightarrow \mathbb{R}^4$

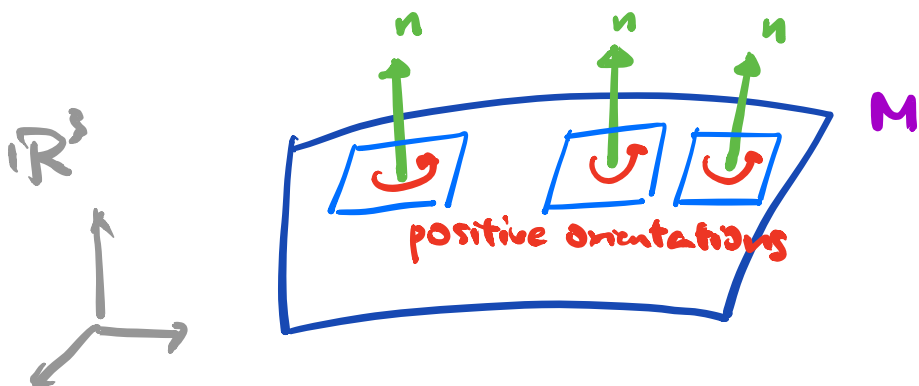
$$g(u, v) = \left(\frac{1}{\sqrt{2}} \cos u, \frac{1}{\sqrt{2}} \sin u, \frac{1}{\sqrt{2}} \cos v, \frac{1}{\sqrt{2}} \sin v \right)$$

Then, the area of M is given by

$$\text{Area}(M) = \int_0^{2\pi} \int_0^{2\pi} \sqrt{\det \begin{pmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{2} \end{pmatrix}} \, du \, dv = 2\pi^2$$

An **orientation** on M is a continuously choice of "positively" oriented basis on each $T_p M$. If such choice exists, we say M is **orientable**.

For surfaces $M \subseteq \mathbb{R}^3$, this can be alternatively described by a globally defined unit normal n together with the "right hand rule".



FACT: M orientable $\Leftrightarrow \exists$ nowhere vanishing k -form on M

Defⁿ: Let $M \subseteq \mathbb{R}^n$ be an oriented k -submanifold.

The **volume form** of M is a k -form σ with the property that

$$\sigma(p)(\underbrace{v_1, \dots, v_k}_{\text{vectors in } T_p M}) = \text{Signed volume of parallelepiped spanned by } v_1, \dots, v_k$$

We now move on to discuss how to integrate k -forms on k -dimensional submanifolds $M \subseteq \mathbb{R}^n$.

For an n -form $\omega = f(x) dx_1 \wedge \dots \wedge dx_n$ in a domain $\Omega \subseteq \mathbb{R}^n$, we define:

$$\int_{\Omega} \omega := \int_{\Omega} f dV$$

Then, the Change of Variable Theorem can be expressed as: $g: \Omega \subseteq \mathbb{R}^n \rightarrow g(\Omega) = S \subseteq \mathbb{R}^n$

$$\int_S \omega = \int_{\Omega} g^* \omega$$

where

$$\omega = f(x) dx_1 \wedge \dots \wedge dx_n$$

$$\left(\begin{array}{l} \text{Reason: } g^*(dx_1 \wedge \dots \wedge dx_n) \\ = \det(Dg) dx_1 \wedge \dots \wedge dx_n \end{array} \right)$$

Defⁿ: Given a parametrization $g: U \rightarrow \mathbb{R}^n$ of a k -dim'l submanifold $M = g(U)$ and a k -form ω in \mathbb{R}^n , we define

$$\int_M \omega := \int_U g^* \omega$$

Integral of k -forms on k -submanifolds

Consequence: Suppose $g_1: U_1 \rightarrow \mathbb{R}^n$, $g_2: U_2 \rightarrow \mathbb{R}^n$ are parametrizations of the same k -submanifold M , then by Change of Variable Theorem,

$$\int_{U_1} g_1^* \omega = \int_{U_2} g_2^* \omega$$

Hence, the definition above is independent on the choice of parametrization. From this, we can define the integral of k -forms on a k -dim'l submanifold which is not necessarily covered by one parametrization.

The "trick" is again "Partition of unity"

Fact: Let $M \subseteq \mathbb{R}^n$ be a compact k -dim'l submfd with boundary. THEN, \exists smooth functions

$$f_i: M \rightarrow [0, 1], \quad i=1, \dots, N$$

each f_i is supported in some parametrization

$$\text{and} \quad \sum_{i=1}^N f_i(x) = 1 \quad \forall x \in M$$

Defⁿ: Let $M \subseteq \mathbb{R}^n$ be a compact, oriented, k -dim'l submanifold with boundary, and ω be a k -form on \mathbb{R}^n . Suppose $\{f_i\}_{i=1}^N$ is a partition of unity as above and $\text{spt}(f_i)$ is contained in the parametrization $g_i: U_i \rightarrow \mathbb{R}^n$ which is "orientation-preserving". THEN, we define

$$\int_M \omega = \sum_{i=1}^N \int_{g_i(U_i)} f_i \omega$$